Numerical Modelling

Jonathan GULA gula@univ-brest.fr Quentin Jamet Quentin.jamet@shom.fr

the anatomy of an ocean model



• Lesson 1 : [D109]

- Introduction
- Equations of motions
- Activity 1 [run an ocean model]

• Lesson 2 : [B014]

- Horizontal Discretization
- Activity 2 [Dynamics of an ocean gyre]

• Lesson 3 : [D019]

- Presentation of the model CROCO
- Dynamics of the ocean gyre
- Activity 2 [Dynamics of an ocean gyre]

• Lesson 4 : [D109]

- Numerical schemes
- Activity 3 [Impacts of numerics]

• Lesson 5 : [D109]

- Vertical coordinates
- Activity 3 [Impact of topography]

• Lesson 6 : [D109]

- Boundary Forcings
- Activity 4 [Design a realistic simulation]
- Lesson 7 : [D109]
 - Diagnostics and validation
 - Activity 5 [Analyze a realistic simulation]

• Lesson 8 : [D109]

Work on your projet

Presentations and material will be available at : jgula.fr/ModNum/

https://github.com/quentinjamet/ Tuto/tree/main/ModNum

Useful references

Extensive courses:

• MIT:

https://ocw.mit.edu/courses/earth-atmospheric-and-planetary-sciences/12-950-atmospheric-and-oceani c-modeling-spring-2004/lecture-notes/

• Princeton: <u>https://stephengriffies.github.io/assets/pdfs/GFM_lectures.pdf</u>

Overview on ocean modelling and current challenges:

- Griffies et al., 2000, Developments in ocean climate modelling, Ocean Modelling. <u>http://jgula.fr/ModNum/Griffiesetal00.pdf</u>
- Griffies, 2006, "Some Ocean Model Fundamentals", In "Ocean Weather Forecasting: An Integrated View of Oceanography", 2006, Springer Netherlands. <u>http://jgula.fr/ModNum/Griffies_Chapter.pdf</u>
- Fox-Kemper et al, 19, "Challenges and Prospects in Ocean Circulation Models" <u>http://jgula.fr/ModNum/FoxKemperetal19.pdf</u>

ROMS/CROCO:

- https://www.myroms.org/wiki/
- Shchepetkin, A., and J. McWilliams, 2005: The Regional Oceanic Modeling System (ROMS): A splitexplicit, free-surface, topography-following- coordinate ocean model. Ocean Modell. <u>http://jgula.fr/ModNum/ShchepetkinMcWilliams05.pdf</u>

Master's degree 2nd year Marine Physics

Jonathan GULA gula@univ-brest.fr

(See chapter 3 of Cushman-Roisin and Beckers)

Ingredients : rotation + stratification



(See chapter 3 of Cushman-Roisin and Beckers)

[XX equations for the XX variables: ...]

(See chapter 3 of Cushman-Roisin and Beckers)

- Momentum equations (3d)
- Conservation of mass
- Conservation of heat
- Conservation of salinity
- Equation of state :

 $\frac{D\vec{u}}{Dt} = \dots$ $\partial_t \rho + \nabla . (\rho \vec{u}) = 0$

$$\begin{aligned} \frac{DT}{Dt} &= \mathcal{S}_T \\ \frac{DS}{Dt} &= \mathcal{S}_S \\ \rho &= \rho(T, S, p) \end{aligned}$$

[7 equations for the 7 variables: u,v,w,p,T,S,p]

(See chapter 3 of Cushman-Roisin and Beckers)

- Momentum equations (3d)
- Conservation of mass
- Conservation of heat
- Conservation of salinity
- Equation of state :

 $\frac{DT}{Dt} = S_T$ $\frac{DS}{Dt} = S_S$ $\rho = \rho(T, S, p)$

 $D\vec{u}$

 $\partial_t \rho + \nabla . (\rho \vec{u}) = 0$

- [7 equations for the 7 variables: u,v,w,p,T,S,p]
- → Cannot be integrated forward in time consistently We need further approximations

(See chapter 3 of Cushman-Roisin and Beckers)

- The different approximations to obtain HPE:
 - Adiabatic motion $\partial_{\theta} \rho|_{S,P} = \partial_{S} \rho|_{\theta,P} = 0$
 - Boussinesq approximation (Incompressible flow) $\rho(x,y,z,t) = \rho_0 + \rho'(x,y,z,t)$
 - Hydrostatic approximation

$$\delta = \frac{H}{L} = \frac{W}{U} \ll 1$$

 $(\widetilde{f} w, \widetilde{f} u) \ll (fu, fv)$

- Traditional approximation (Horizontal Coriolis)

- Navier-Stokes Equations (NS)
- Non-hydrostatic Primitive Equations (NH)
- Hydrostatic Primitive Equations (PE)
- Shallow-water (SW)
- Quasi-geostrophic (QG)
- 2D Euler equations
- Etc.



Navier-Stokes Equations:

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + g\vec{k} = -\frac{\vec{\nabla}P}{\rho} + \vec{\mathcal{F}}$$

Momentum equations

 $\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$

Mass conservation (no source/sink)



$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} = 0$$

Mass conservation (no source/sink)

Navier-Stokes Equations:

Linearized momentum equations

- + continuity equation
- + adiabatic motion :

= Acoustic modes (sound waves)

$$\begin{array}{rcl}
\rho_0 \frac{\partial \vec{u}}{\partial t} &=& -\vec{\nabla}P\\ \frac{\partial P}{\partial t} &=& -\rho_0 c_s^2 \vec{\nabla}P \cdot \vec{u}\\ \end{array}$$

 $\partial_{tt}P = c_s^2 \nabla^2 P$

With $c_s \approx 1500 \,\mathrm{m\,s}^{-1}$ in water, a model requires a very small time-step to solve these equations.

 \rightarrow Ex: sound waves would take about 1/30 sec to cross a 50-m long swimming pool

Boussinesq Approximation:

Density perturbations small compared to mean background value:

$$\rho = \rho_0 + \rho' \qquad \qquad \rho' << \rho_0$$

Linearize all terms involving a product with density,

except the gravity term which is already linear:

$$\begin{array}{ccc} \rho \vec{u} & \rightarrow & \rho_0 \vec{u} \\ \rho g & \rightarrow & \rho g \end{array}$$

Boussinesq Approximation :

[+ incompressibility or adiabatic]

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \rho \vec{u} &= 0 \\ & \int & \int & \partial_t \rho + \nabla \cdot \rho \vec{u} &= \partial_t \rho + \rho \nabla \cdot \vec{u} + \vec{u} \nabla \rho \\ &= (\rho_0 + \rho') \nabla \cdot \vec{u} + D_t \rho' \\ &\sim \rho_0 \nabla \cdot \vec{u} \end{aligned}$$

Mass conservation → Volume conservation

Non hydrostatic boussinesq (NH):

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} + 2\vec{\Omega} \times \vec{u} + \frac{\rho}{\rho_0} g\vec{k} = -\frac{\vec{\nabla} P}{\rho_0} + \frac{\vec{\mathcal{F}}}{\rho_0} + \frac{\vec{\mathcal{D}}}{\rho_0}$$
$$\vec{\nabla} \cdot \vec{u} = 0$$

Easier to solve than Navier-Stokes, but still requires to invert a 3d elliptic equation for P (computationally expansive)

Hydrostatic balance:

The vertical component of the Boussinesq momentum equations is

$$\partial_t w + \vec{u} \cdot \vec{\nabla} w + 2\Omega \cos \phi u + \frac{\rho}{\rho_0} g = \frac{1}{\rho_0} \partial_z P + F_w + D_w$$

 $P = \int g \rho dz$

For long horizontal motions (L >> H) the dominant balance is

H~3000 m
L~3000 km
$$\frac{\partial P}{\partial z} = -\rho g$$

Such that pressure is just a vertical integral:



Hydrostatic Primitive Equations (PE)

2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - fv = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$
$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + fu = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$
Hydrostatic:
$$\frac{\partial P}{\partial z} = -\rho g$$

• Continuity equation for an incompressible fluid: $ec{
abla}\cdotec{u}=0$

Hydrostatic Primitive Equations (PE)

2d momentum with Boussinesq approximation:

$$\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} - fv = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$$
$$\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + fu = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$$
$$\frac{\partial P}{\partial z} = -\rho g$$

 ∂z

 $\frac{DT}{Dt} = \mathcal{S}_T \qquad \frac{DS}{Dt} = \mathcal{S}_S$

 $\vec{\nabla} \cdot \vec{u} = 0$

- Hydrostatic:
- Continuity equation for an incompressible fluid:
- Conservation of heat and salinity
- Equation of state : $\rho = \rho(T, S, z)$

Hydrostatic Primitive Equations (PE)

- 4 prognostics equations for **u**, **v**, **T**, **S**
- 3 diagnostics equations for w, p, P

 $\frac{\partial P}{\partial z} = -\rho g$

 $\frac{DT}{Dt} = \mathcal{S}_T \qquad \frac{DS}{Dt} = \mathcal{S}_S$

 $\vec{\nabla} \cdot \vec{u} = 0$

- Hydrostatic Primitive Equations (PE)
- 2d momentum with Boussinesq approximation:
 - $\frac{\partial u}{\partial t} + \vec{u} \cdot \vec{\nabla}_H u + w \frac{\partial u}{\partial z} fv = -\frac{\partial_x P}{\rho_0} + \mathcal{F}_u + \mathcal{D}_u$ $\frac{\partial v}{\partial t} + \vec{u} \cdot \vec{\nabla}_H v + w \frac{\partial v}{\partial z} + fu = -\frac{\partial_y P}{\rho_0} + \mathcal{F}_v + \mathcal{D}_v$
- Hydrostatic:
- Continuity equation for an incompressible fluid:
- Conservation of heat and salinity
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Hydrostatic Primitive Equations (PE)

- 4 prognostics equations for **u**, **v**, **T**, **S**
- 3 diagnostics equations for w, p, P

+ Forcings (wind, heat flux)

+ sub-grid scale parameterizations (bottom drag, mixing, etc.)

Activity 1 – Run an idealized ocean basin SSH



Activity 1 – Run an idealized ocean basin

- Jobcomp (compilation)
- cppdefs.h (Numerical/physical options)
- param.h (gris size/ parallelisation)
- <u>croco.in</u> (choice of variables, parameter values, etc.)

Activity 1 – Run an idealized ocean basin

https://github.com/quentinjamet/Tuto

1) Preparing and compiling the model

For that use the the jobcomp bash file ./jobcomp

- 1. Set library path
- 2. Automatic selection of option accordingly the platform used
- 3. Use of makefile
 - C-preprocessing step : .F → .f using the CPP keys definitions (in cppdefs.h file, customization of the code)
 - Compilation step : $.f \rightarrow .o$ (object) using Fortran compiler
 - Linking step : link all the .o file and the librairy (Netcdf, MPI, AGRIF)
 - --> produce the executable roms

1) Preparing and compiling the model

Edit the param.h and cppdefs.h file to set-up the model

param.h defines the size of the arrays in ROMS:



- Define CPP keys used by the C-preprocessor when compiling the model.
- Reduce the code to its minimal size: fast compilation.
- Avoid FORTRAN logical statements: efficient coding.

1) Preparing and compiling the model

View cppdef.h file

BASIC OPTIONS MORE ADVANCED OPTIONS */ */ /* /* Configuration Name */ # define SOLVE3D # define BENGUELA # define UV COR /* Parallelization */ # define UV ADV # undef OPENMP # ifdef TIDFS # define SSH TIDES # undef MPI # define UV TIDES Embedding */ /* # define TIDERAMP # undef AGRIF # endif Open Boundary Conditions */ /* /* # define CURVGRID # undef TIDES # define SPHERICAL # define OBC EAST # define MASKING # undef OBC WEST /* # define OBC NORTH # define AVERAGES # define OBC SOUTH # define AVERAGES K # define DIAGNOSTICS TS */ Embedding conditions */ # ifdef AGRIF /* # undef AGRIF_OBC_EAST /* # define AGRIF_OBC_WEST /* # define AGRIF OBC NORTH /* * # define AGRIF OBC SOUTH /* # endif /* /* Applications */ /* # undef BIOLOGY /* /* # undef FLOATS # undef STATIONS # undef PASSIVE TRACER # undef SEDIMENTS # undef BBL

Model dynamics */ Grid configuration */ Input/Output & Diagnostics */ # define DIAGNOSTICS UV Equation of State */ ... Surface Forcing */ ... Lateral Forcing */ ... Input/Output & Diagnostics */ ... Bottom Forcing */ ... Point Sources - Rivers */ ... Lateral Mixing */ ... Vertical Mixing */ ... Open Boundary Conditions */ ...

Embedding conditions */ ...

2) Running the model

The namelist roms.in

roms.in provides the run time parameters for ROMS:

title: Southern Benguela time stepping: NTIMES dt[sec] NDTFAST NINFO 5400 60 480 1 S-coord: THETA S, THETA B, Hc (m) 6.0d0 0.0d0 10.0d0 grid: filename Warning ! These ROMS FILES/roms grd.nc should be identical to forcing: filename the ones in ROMS FILES/roms frc.nc bulk forcing: filename romstools_param.m ROMS FILES/roms blk.nc climatology: filename ROMS_FILES/roms_clm.nc boundary: filename ROMS FILES/roms bry.nc initial NRRFC filename 1 ROMS FILES/roms ini.nc NRST, NRPFRST / filename restart: 480 -1 ROMS FILES/roms rst.nc

history: LDEFHIS, NWRT, NRPFHIS / filename T 480 0 ROMS FILES/roms his.nc averages: NTSAVG, NAVG, NRPFAVG / filename 48 0 1 ROMS FILES/roms avg.nc primary history fields: zeta UBAR VBAR U V wrtT(1:NT) T F F F F 10*F auxiliary history fields: rho Omega W Akv Akt Aks HBL Bostr FFFFFFFF primary averages: zeta UBAR VBAR U V wrtT(1:NT) T T T T T 10*T auxiliary averages: rho Omega W Akv Akt Aks HBL Bostr FTTFTFTT rho0: 1025.d0 lateral_visc: VISC2, VISC4 [m^2/sec for all] 0 0 tracer diff2: TNU2(1:NT) [m²/sec for all] 10*0.d0 bottom drag: RDRG [m/s], RDRG2, Zob [m], Cdb min, Cdb max 0.0d-04 0.d-3 1.d-2 1.d-4 1.d-1 gamma2: 1.d0 X SPONGE [m], V SPONGE [m²/sec] sponge: 800 100.e3

nudg_cof: TauT_in, TauT_out, TauM_in, TauM_out [days for all] 1. 360. 10. 360.

Activity 1 – Run an idealized ocean basin

• param.h

parameter (LLm0=60, MMm0=50, N=10)

· cppdefs.h

define UV_COR
define UV_VIS2
define TS DIF2

define ANA_GRID
define ANA_INITIAL

• ana_grid.F

f0=1.E-4 beta=0.

· croco.in

 bottom_drag:
 RDRG(m/s), RDRG2, Zob [m], Cdb_min, Cdb_max

 3.e-4
 0.
 0.
 0.

 gamma2:
 1.

 lin_EOS_cff:
 R0 [kg/m3], T0 [Celsius], S0 [PSU], TCOEF [1/Celsius], SCOEF [1/PSU]

 30.
 0.
 0.28
 0.

 lateral_visc:
 VISC2 [m^2/sec]
 1000.0.
 0.

 tracer_diff2:
 TNU2
 [m^2/sec]
 1000.0.

Homework

- For next time:
 - Read <u>https://www.jgula.fr/ModNum/Stommel48.pdf</u>
 - Read <u>https://www.jgula.fr/ModNum/Munk50.pdf</u>